EECS-340 Introduction to Computer Networking Lecture 7: TCP Congestion Control

Steve Tarzia

Many diagrams & slides are adapted from those by J.F Kurose and K.W. Ross

Last Lecture: TCP

- Uses cumulative ACKs. Any data segment can carry an ACK.
- Receivers buffer out-of-order (early) segments for later reassembly.
- ACK timeout can be appropriately set with Exponentially-Weighted Moving Average (**EWMA**) of recent RTT and recent **jitter**.
- # in-flight packets (thus throughput) is determined by *window size*.
- TCP throughput should be regulated so as not to overwhelm:
 - the receiver -- Flow control is implemented with explicit Receive Window.
 - the network Congestion control (today's topic).
- Connection setup requires a 3-way handshake.
 - Sets initial sequence numbers and receive windows in both directions.
 - Teardown requires sending and acknowledging **FIN** messages.

Congestion Control

- Congestion is when the **network** is overloaded
 - Router queues are full, so packets are dropped
 - or length of queues leads to long nodal queuing delay, causing timer to expire.
- Dropped packets lead to *inefficiency* and can compound the problem:
 - Congestion \rightarrow Packet loss \rightarrow Retransmission \rightarrow *More congestion!* \rightarrow *More loss!*
- Goal is to prevent the self-destructive feedback cycle above.
- *Better to wait* than to send a packet likely to be dropped before reaching its destination.
- We have **end-to-end observations** of network performance, but the precise internal cause of a network problem is difficult to know.
 - State of routers along path is unknown end hosts know only their state.

What would happen without congestion control?

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- Problems arise even in a simple network with just one connection/flow:
- If links have different bitrates, and hosts send as fast as possible, packet loss will occur:



- Very large buffers would be needed, with many gaps for lost packets.
- Cumulative ACKs (as in TCP) would not be efficient:
- "Early" segments would be common, and these would all be retransmitted.

Shared congestion causes more inefficiency

It's wasteful to drop packets dropped halfway through their trip.

- Below, assume all links have a capacity of 10.
- E cannot communicate with C simply because B is wasting bandwidth on the middle diagonal link. Half of the B to D packets are dropped anyway.



Two general types of congestion control

End-to-end (TCP)

- No explicit feedback from routers.
- Congestion is inferred from observed packet loss.

Network assisted

- Routers signal congestion:
 - Sets a certain bits in TCP (or IP) header (called ECN)
 - List precise bitrate desired for sender.
- This has become popular within cloud/datacenter networks.
 - Requires routers to be properly configured and trusted.

Observing congestion

- Recall that flow control (receive window) prevents loss at receiver.
- If packets are dropped (timers expire before ACK), two possibilities:
 - Timer interval is too small (EWMA will adjust itself), or
 - The network is congested, and packets are being dropped by routers.

Basic idea of TCP congestion control:

- Sender tries to estimate an appropriate congestion window (cwnd)
- # in-flight packets \leq MIN(cwnd, rwnd) \leftarrow rwdn is flow control's "receive window"
- Larger cwnd \rightarrow greater throughput, greater load on network
- When senders observes packet loss, decrease cwnd.

Precise details are open to debate, RFCs make recommendations.

Key Challenge: sender's choice of congestion window size

TCP "Reno"



TCP Reno congestion control operates in phases

- 1. Slow start: initially, network capacity is unknown, so start with cwnd=MSS (maximum segment size ~= 1460 bytes), send 1 packet.
 - *Double* cwnd each time an ACK is received (every RTT). This leads to *exponential growth* in cwnd.
 - Loss by timeout \rightarrow ssthresh = cwnd/2
 - If cwnd > ssthresh, move to Congestion Avoidance mode.
- 2. In Congestion Avoidance mode:
 - ACK received \rightarrow cwnd += MSS There is *linear growth* in cwnd.
 - Loss by timeout → *reset* cwnd = MSS, and move back to *slow start* mode Timeout indicates a serious network problem
 - On loss by triple-duplicate ACK, move to third phase:
- 3. Fast Recovery Mode:
 - Some packets are still getting through, so don't over-react. Cut cwnd in *half*.
 - cwnd = cwnd/2
 - ACK received \rightarrow move to *congestion avoidance* mode



TCP Reno throughput

• Slow start, then congestion avoidance:

What's Reno's steady-state throughput?

and HIN

- In congestion avoidance steady state, throughput is approximately ³/₄ of the max.
 - Throughput increases linearly until congestion occurs, and it's halved.



Steve's Haircut Algorithm A TCP congestion control analogy



Incentive to follow TCP rules?



Following the rules benefits everyone, but also benefits yourself.

- If I don't throttle myself during congestion, then I will have poor performance in cases when I am the only host causing the congestion.
 - This is is often the case when the first or last hop is the "bottleneck."
- Hosts cannot observe the network directly, just observe packet losses.
 - I cannot tell whether others' traffic is contributing to congestion or whether it's just my own traffic causing the congestion (and thus packet loss).
- Thus, everyone will reduce throughput when congestion occurs, just in case they are solely responsible for the congestion.
- Also, there are only a few TCP implementations, supplied by operating systems, so they generally follow an RFC's recommendations.

TCP Reno congestion control iteration

The diagram shows two connections sharing a link/path with limited capacity:



Connection 2 throughput

- How does the throughput of connections 1 and 2 evolve over time?
- Remember that the two connections follow the TCP rules independently.
- Each controls its own throughput (congestion window size), but is unaware that the other connection.
 - Don't know other connection's cwnd.
 - Don't even know other connection exists!
- Initially 1 is faster than 2, how does this change?
 - Where does the point move?



Reno eventually leads to equal share of bandwidth



Figure 3.55 • Throughput realized by TCP connections 1 and 2

- During congestion, packets are dropped and bandwidth (window sizes) are cut in half.
 - Connection with more bandwidth share *always loses more* when window is cut in half.
 - Move halfway toward the origin in the plot.
- During congestion avoidance, bandwidth of both connections increases at the same rate, moving at 45° angle up-right.

Intermission

Driving past Reno

- TCP congestion control in the Linux kernel can use many algorithms.
 - They can be dynamically switched by the user. For example: \$ echo "cubic" > /proc/sys/net/ipv4/tcp_congestion_control
- TCP congestion algorithm in open source OSes has evolved like so:
 - Tahoe: BSD 4.3 Tahoe (1988)
 - Reno: BSD 4.3 Reno (1990)
 - <u>New Reno</u> with SAC: Linux 2.4?–2.6.17 (2001?–2004)
 - **BIC**: Linux 2.6.8–2.6.18 (2004–2006)
 - **CUBIC**: Linux 2.6.19–3.2 (2006–2012)
 - **PRR**: Linux 3.2–4.9 (2012–2016)
 - **BBR**: Linux 4.9–present (2016–present)

Problems with TCP Reno

- In congestion avoidance, linear increase is too slow on fast, high latency links (long fat pipes)
- Consider a 10Gbps link with 30ms RTT.
 - Increasing window linearly (1500 bytes per RTT) would require **3.5** hours to move from 5 to 10 Gbps.
 - This is especially bad if we lose packets due to bit corruptions:
 - In 3.5 hours 100 trillion bits will be sent!
 - Perfect reliability on that scale is unlikely.
- Solution: grow faster!

• Binary Increase (BIC) and CUBIC congestion control use a kind of binary search to *exponentially* grow the window:



Packet loss means full queues and wasted time!

- Reno and CUBIC both rely on packet loss to detect congestion.
- They keep the links busy by moving between states 2 and 3:
- **Bufferbloat** is the unnecessary delay added to RTT because router buffers are too large.
- It would be better to operate between states 1 and 2.
- Throughput would still be high, but without queueing delays.



• There is no packet loss until we get to state 3, so what else can we monitor to detect state 2?



Vegas and BBR Congestion Control

- The RTT of packets can give information about queue states.
- TCP Vegas introduced the idea of looking for increases in RTT (instead of packet loss) as a signal of congestion.
 - If we're below the max throughput, RTT should be fixed.
 - When we send above the max throughput, queues start to fill and RTT rises.
 - Vegas achieves throughput near the maximum while keeping router buffers nearly empty. **RTT is optimized,** not just throughput.
 - Unfortunately, Vegas flows do not get a fair share of capacity when competing with Reno and CUBIC flows.
- **BBR** (Bottleneck Bandwidth and Round-trip propagation time) fixes this shortcoming and seems to be the best approach so far.
 - We will not cover its details. It was published by Google in 2016.

BBR in action



Time

A few final tweaks for TCP

Nagle's algorithm merges small packets

- An application may write a series of small message to a TCP stream.
 - Eg: write ("OK\n"); write ("READY\n"); write ("GO\n");
- A simple implementation of TCP would send segments for each write.
- But each TCP packet has 40 bytes of *header overhead*.
 - Merging small packets into one larger packet would reduce network load:

Total size includes three
headers before merging:
$$(40+3) + (40+6) + (40+3) \rightarrow (40+12)$$
$$132 \rightarrow 52 \text{ bytes}$$

• Wait until segment is full before sending, *unless* there are no un-ACK'ed segments outstanding (eg., send first segment immediately).

Interactive applications

- Interactive apps and bulk-transfer apps prefer different TCP behavior.
- Socket options give applications some control of the underlying TCP:
- TCP_NODELAY socket option disables Nagle's algorithm.
 - Every *write* \rightarrow segment(s) are sent immediately (if allowed by window).
 - Nagle's algorithm adds extra latency which may hurt performance of applications that send small, *time-sensitive* data. (eg., GUI events).
- TCP_NOPUSH is even more aggressive than standard Nagle.
 - Wait until send buffer is full before sending segment(s).
 - Also, don't set PSH bit (to maximize buffering on the receiver's side as well).
- Usually the **PSH bit** will be set on the last segment in a *write* call.
 - PSH tells the receiving TCP implementation to alert the receiving process that that data is ready.

TCP Keepalive

- An *idle* TCP connection involves no data exchange.
- Optionally, a TCP host may occasionally send an empty data segment, called a **keepalive message**, just to test whether an ACK will return.
 - Keepalive has SEQ # one less than expected, to trigger an ACK response.
 - Low frequency, ~once per minute.
- Keepalives are disabled by default and only used in special situations:
 - SSH clients give the option to enable TCP keepalives.
 - This forces NAT routers to keep the port mapping alive.
- Some application-level protocols have their own keepalive msgs.

TCP Recap

- Congestion control is implemented with a dynamic *congestion window*, controlled by *heuristics*. Reno congestion control operate in phases:
 - *Slow start* exponential growth to find approximate network capacity.
 - Congestion avoidance linear growth, slowly trying to increase throughput.
 - *Fast recovery* If one packet is lost, then cut window in half.
- Additive Increase, Multiplicative Decrease ensures fair sharing.
- **CUBIC** and **BBR** are newer alternatives that work better in fast networks, particularly long fat pipes. (Read <u>this</u> for more info.)
- TCP behavior can be controlled with socket options:
 - Nagle's algorithm merges small packets to reduce *header overhead*.
 - TCP *keepalive* message can be periodically sent.